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EFFICIENCY TECHNOLOGY POTENTIAL FOR HEAVY-DUTY DIESEL VEHICLES IN THE UNITED STATES THROUGH 2035

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EXECUTIVE SUMMARY

Heavy-duty vehicles in the United States are subject to increasingly stringent fuel efficiency and greenhouse gas standards. Set by the Environmental Protection Agency (EPA) and the National Highway Traffic Safety Administration, the current Phase 2 standards extend through model year 2027. Most heavy-duty vehicles on the road today are powered by diesel-fueled internal combustion engines and no existing national policy requires a change in this status quo.

This analysis considers the potential for technologies to improve the efficiency of internal combustion engine vehicles beyond the Phase 2 standards and out to model year 2035. We focus on two key vehicle segments: Class 8 high-roof sleeper cab tractor trucks and Class 6-7 multipurpose vocational vehicles. Drawing on previous ICCT and EPA analysis, recent literature, and the latest SuperTruck achievements, we simulate efficiency technologies using the EPA's Greenhous Gas Emissions Model (GEM). We estimate technology costs relative to low-cost compliance with the Phase 2 standard.

For both vehicle segments, engine efficiency improvements deliver the largest efficiency benefits. Low rolling resistance tires, idle reduction technologies, and tractor-trailer aerodynamic improvements are also significant but we assume some of these advances are already deployed to achieve low-cost compliance in model year 2027. For the Class 8 tractor-trailer, we identify cost-effective potential for a 29% increase in fuel economy and a 24% decrease in per ton-mile CO₂ emissions compared to Phase 2 standards, at a marginal cost of \$5,200. Adding mild hybridization and transmission-enabled strategies like engine downspeeding and downsizing, which require more than two years to recoup upfront costs, increases per ton-mile efficiency gains by 10 percentage points and brings the marginal cost up to \$29,300. However, the efficiency benefits of these more expensive technologies are largely erased if trailer technologies are removed, which lowers fuel economy from 13.8 to 12.1 mpg. For the Class 6-7 vocational vehicle, we identify potential for a 44% increase in fuel economy and a 34% decrease in per ton-mile CO₂ emissions from Phase 2. This technology package has a marginal cost of \$15,400 relative to the standard and a cumulative payback period of less than two years.

With the entrance of zero-emission vehicles into the heavy-duty market, future standards may consider the technology potential for both conventional and zero-emission powertrains to reduce greenhouse gas emissions. Given the long lifetime of heavy-duty vehicles, fuel efficiency standards for new diesel vehicles cast a long shadow. Achieving ambitious climate targets requires that the last generations of internal combustion engine vehicles be as fuel-efficient and low-emitting as possible.

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INTRODUCTION

Heavy-duty vehicles were responsible for one-quarter of transport sector greenhouse gas emissions in the United States in 2019, with more than 99% of CO_2 -equivalent emissions emitted directly as CO_2 (U.S. Environmental Protection Agency, 2021). These vehicles, defined as trucks and buses with a gross vehicle weight rating greater than 8,500 pounds, serve a range of commercial vehicle segments from last-mile delivery and refuse pickup to intercity busing and long-haul trucking.

The U.S. Environmental Protection Agency (EPA) and the National Highway Traffic Safety Administration (NHTSA), referred to as "the agencies" in this paper, have historically regulated heavy-duty vehicles with increasingly stringent fuel efficiency and greenhouse gas standards. The first phase of these regulations took effect in model year 2014 and set separate standards for engine and chassis manufacturers (Greenhouse Gas Emissions Standards and Fuel Efficiency Standards for Medium- and Heavy-Duty Engines and Vehicles, 2011). By model year 2017, the overall efficiency of heavy-duty vehicles was required to improve by 6-23% from a 2010 baseline, with the highest percentage improvements required for Class 8 sleeper cab tractors and the lowest for Class 2b-8 vocational vehicles (Sharpe, 2011). The second and most recent phase of these regulations updated the simulation model used for vehicle certification, added a separate standard for trailers, and required further efficiency improvements for engines and vehicles starting in model year 2021 (Greenhouse Gas Emissions and Fuel Efficiency Standards for Medium- and Heavy-Duty Engines and Vehicles-Phase 2, 2016). By model year 2027, these Phase 2 standards will require efficiency improvements of 12-27% from a 2017 baseline.

Figure 1 shows currently adopted Phase 1 and 2 vehicle efficiency standards for two representative vehicle segments, Class 8 high-roof sleeper cab tractor trucks and Class 6-7 multipurpose vocational vehicles, measured in grams of CO_2 per ton-mile $(gCO_2/ton-mi)$. The regulations also specify equivalent standards for fuel consumption, measured in gallons per 1000 ton-miles (gal/1000 ton-mi), using a conversion factor of 10,180 grams of CO_2 per gallon of diesel. The baseline and standards for Phase 1 are not directly comparable to those for Phase 2, which reflect more refined transmission and engine modeling, the inclusion of road grade in drive cycles, and updated aerodynamic test procedures and default trailer settings.

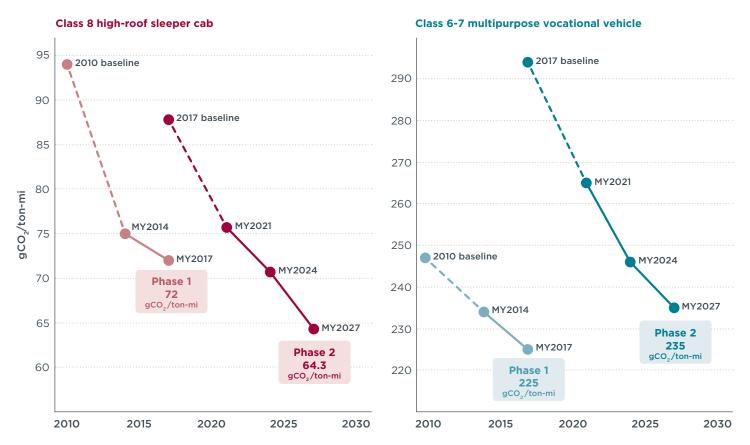


Figure 1. Phase 1 and 2 vehicle efficiency standards for Class 8 high-roof sleeper cab tractor trucks and Class 6-7 multipurpose vocational vehicles. The difference between the 2017 standard in Phase 1 and the 2017 baseline in Phase 2 reflects upgrades to the Greenhouse Gas Emissions Model (GEM), which are detailed in the model documentation and which we have summarized above.

Heavy-duty vehicles (HDVs) have historically been powered by internal combustion engines, which is reflected in the regulatory structure of current fuel efficiency standards. With growing global momentum for a transition to zero-emission technology, future standards may consider the technology potential for both conventional and zero-emission powertrains (Office of Transportation and Air Quality U.S. Environmental Protection Agency, 2021). This analysis focuses on the technology potential remaining for diesel HDVs, as they currently represent more than 99% of the fleet and no existing national policy requires a change in this status quo. Subsequent analyses will evaluate the technology potential, costs, and regulatory considerations for zero-emission HDVs.

Previous ICCT and EPA analyses identified the potential for cost-effective emissions reductions beyond those required for compliance in model year 2027 (Delgado & Lutsey, 2015; Meszler et al., 2015; U.S. EPA, 2015). Using the EPA's Greenhouse Gas Emissions Model (GEM), we build on these earlier analyses to estimate the efficiency technology potential for heavy-duty diesel vehicles out to model year 2035, focusing on the two representative vehicle segments shown in Figure 1 (U.S. Environmental Protection Agency, 2016). We evaluate the cost-effectiveness of each efficiency technology by considering the cost per percent reduction in fuel consumption and the payback period, or the time required to recoup upfront costs with fuel savings. For each vehicle segment, we project efficiency improvements and marginal costs for a single real-world vehicle in model years 2027 and 2035. We compare this technology

potential to the Phase 2 standard for model year 2027, which is based on projected fleet-average technology adoption rates.

In the following sections, we first describe our vehicle simulation modeling tools and baseline vehicle parameters. We then consider the efficiency technologies that could be deployed in model year 2027 and 2035 vehicles, and subsequently evaluate their cost-effectiveness, primarily by extending cost estimates provided in the Phase 2 regulatory documents. We conclude by presenting technology packages that represent incremental improvements in vehicle efficiency in order of technology costeffectiveness and by comparing our results to current Phase 2 standards and previous ICCT analysis.

MODELING TOOLS

The Greenhouse Gas Emission Model (GEM) is the EPA's regulatory model for certifying medium- and heavy-duty vehicle fuel consumption and CO_2 emissions. The tool is used both by the agency to develop greenhouse gas emission standards and by manufacturers to demonstrate compliance with these standards. The model was initially developed during the Phase 1 rulemaking and was updated for the Phase 2 regulation. In this analysis, we use GEM P2v3.5.1, which includes several improvements to the version first published with the Phase 2 rulemaking. Table 1 shows the baseline powertrain configuration we use in GEM for each vehicle segment.

Table 1. Baseline powertrain settings for Class 8 high-roof sleeper cabs and Class 6-7 multipurpose vocational vehicles in this study.

	Class 8 high-roof sleeper cab	Class 6–7 multipurpose vocational vehicle
Engine	15-liter, 455 hp compression-ignition	7-liter, 270 hp compression-ignition
Idle speed	600 revolutions per minute	750 revolutions per minute
Transmission	Manual, 10-speed	Automatic, 6-speed
Transmission gear ratios	12.8, 9.25, 6.76, 4.90, 3.58, 2.61, 1.89, 1.38, 1.00, 0.73	3.102, 1.8107, 1.4063, 1.0, 0.7117, 0.61
Rear axle ratio	3.70	5.29
Loaded tire size	512 revolutions per mile	557 revolutions per mile

In GEM, vehicle efficiency is calculated as a weighted average over three specific drive cycles: the California Air Resources Board's heavy heavy-duty diesel truck (HHDDT) transient cycle and two constant speed 55-mph and 65-mph cycles with variable road grade (GEM 55 mph and GEM 65 mph). For vocational vehicles,¹ efficiency is additionally weighted over two idle cycles, representing idling while parked and while in traffic. These drive and idle cycle weightings for the two vehicle segments we analyze here are listed in Table 2, adding up to 100%.

¹ Vocational vehicles are a broad category of heavy-duty vehicles, including those vehicles not categorized as Class 2b-3 pickup trucks and vans or as Class 7-8 combination tractors. They include vehicles such as larger vans and trucks, utility bucket trucks, refuse trucks, and urban buses.

Table 2. GEM parameters for Class 8 high-roof sleeper cabs with long dry box trailers and Class 6–7 multipurpose vocational vehicles in the Phase 2 regulation.

	Class 8 high-roof sleeper cab	Class 6–7 multipurpose vocational vehicle
Drive and idle cycles ^a	5% HHDDT transient 9% GEM 55 mph 86% GEM 65 mph	31% HHDDT transient 13% GEM 55 mph 13% GEM 65 mph 25% parked idle 17% drive idle
Curb weight	32,500 lbs (14,742 kg)	13,950 lbs (6,328 kg)
Payload	38,000 lbs (17,237 kg)	11,200 lbs (5,080 kg)
Total weight	70,500 lbs (31,978 kg)	25,150 lbs (11,408 kg)
Gear efficiency	100% for direct drive, 98% for high gears, 96% for low gears	99.5% for direct drive, 98% for other gears
Tire rolling resistance weighting	15% steer tires 42.5% drive tires 42.5% trailer tires	30% steer tires 70% drive tires
Default trailer settings	6 kg/t tire rolling resistance -0.3 m² delta C _d A for trailer skirt	-
Frontal area	10.4 m ²	5.4 m ²
Weight reduction distribution	One-third added to payload, two-thirds reduced from total vehicle weight	One-half added to payload, one-half reduced from total vehicle weight
Accessory power load	1.2 kW electrical 2.3 kW mechanical	0.9 kW electrical 1.6 kW mechanical

^a Vocational vehicle cycle weights do not add up to 100% due to rounding.

The model is structured to implement certain efficiency technologies based on a set of underlying assumptions. All high-roof tractor-trailers are simulated with a 53-foot dry box van trailer, which includes aerodynamic side skirts as part of the default aerodynamic drag area (C_dA). The rolling resistance coefficient (C_{rr}) for tires is modeled as a weighted average of steer, drive, and trailer tire coefficients, with weighting factors varying by vehicle segment. In addition, lightweighting is implemented in GEM such that only part of the applied weight reduction decreases the total weight of the vehicle and the remainder serves to increase payload. This reflects two ways in which lightweighting may improve vehicle efficiency: first, by reducing the road load (decreased weight) and second, by reducing the total number of trips needed along a given route (increased payload). In GEM, an increase in payload delivers a greater per-ton-mile efficiency gain than an equivalent decrease in vehicle weight. In practice, however, the effectiveness of lightweighting depends heavily on whether a vehicle is weight- or space-limited.

Many efficiency technologies can be implemented directly based on user-provided input data, such as engine efficiency improvements, transmission type, axle ratios, aerodynamic drag, weight reduction, and neutral idle. For vocational vehicles, stopstart and automatic engine shutdown technology can also be implemented directly. Several other technologies are implemented indirectly by specifying technology improvement multipliers that are applied to the simulation results, such as tire pressure systems, accessory loads, predictive cruise control, and extended idle reduction. The Phase 2 rulemaking pre-defines improvement values for these technologies. We align with these values except when further advances are anticipated, and we note when this is the case. Mild hybridization cannot be simulated directly in GEM. For tractor-trailers, efficiency improvements are derived from independent modeling and are applied as a post-processing factor. To calculate efficiency gains from regenerative braking energy as captured with a mild hybrid system, we employ Simcenter Amesim, a physics-based simulation tool that supports integrated assessment of vehicle performance. We use the tool to simulate a diesel vehicle that mimics the corresponding vehicle simulation in GEM. This simulation provides high resolution data on power demand and losses, from which we calculate the potential for recovery of braking losses based on a given battery capacity and power rating. For vocational vehicles, the agencies estimate efficiency savings from mild hybridization with engineering calculations. We conservatively apply this value, which is roughly comparable to our own simulations.

TECHNOLOGY IMPROVEMENTS

The EPA's current vehicle efficiency standards are technology-neutral, such that compliance can be demonstrated with a range of technology packages. The standards themselves are set by weighting the efficiency improvement associated with individual technologies by their projected fleet-wide adoption rates. We draw on previous ICCT analysis to define a low-cost technology package that achieves compliance with the model year 2027 standard in each segment (Sharpe et al., 2018). This allows us to compare efficiency improvements and cost-effectiveness beyond Phase 2 to a single, real-world vehicle. We compare this low-cost compliance scenario with the technology adoption assumed in the Phase 2 standards and then estimate technology potential out to model year 2035.

For Class 8 high-roof sleeper cabs, we include trailer efficiency technologies but highlight tractor-only technology potential in our results, with more detail in the Appendix. To compare with tractor and trailer standards, we use the GEM inputs specified in the Phase 2 rulemaking to simulate a single tractor-trailer representing both standards in model year 2027. This combined standard is 57.7 gCO_2 /ton-mi, roughly 10% lower than the tractor standard.

TRACTOR-TRAILERS

The technology adoption rates for the Phase 2 standard in model year 2027 are shown in Table 3, alongside the technology packages assumed for low-cost compliance and our estimate of the technology potential out to 2035. These assumptions are described in more detail below. Figure 2 shows efficiency improvements by technology area in each modeling scenario, relative to the Phase 2 standard. Tractor-only efficiency improvements and a summary of the 2010 baseline for tractor-trailers can be found in the Appendix. **Table 3.** Class 8 high-roof sleeper cab tractor-trailers technologies and adoption rates projected under the Phase 2 standard, compared to low-cost compliance in 2027 and our assumed technology potential in 2035. Technologies not considered in the Phase 2 rulemaking are highlighted in yellow. Tire rolling resistance levels and aerodynamics bins are listed in Table A1 in the Appendix.

	Dhasa	2 stan	ما م بر ما ا	- 2027		t oo muuli			Teehnel		ial in 2075
Engine	Phase	2 stan	dard II	12027	Low-cos	t compil	ance in 2027		Technolo	ogy poten	tial in 2035
2027 compliant engine (49% peak BTE)		×	<	_	_	Х			_	_	
Advanced engine (55% peak BTE)						~				Х	
Transmission ^a										~	
Manual						Х					
Automatic (with neutral idle)		30)%			~					
Automated manual		50									
Dual clutch		10								х	
		70								X	
1% gear efficiency improvement		50				Х				×	
Top gear direct drive		50	J%			~				X	
Mild hybrid (PO configuration) Transmission-enabled	_									~	
			_	_		X	_		_	_	_
2.70 final drive ratio baseline						Х					
2.31 final drive ratio		X	<								
1.96 final drive ratio										Х	
10% engine downsizing										Х	
Idle reduction											
Tamper-proof AESS						Х					
Adjustable AESS		15	%								
Adjustable AESS + diesel auxiliary power unit (APU)		40								Х	
Adjustable AESS + battery APU		15	5%								
Adjustable AESS + automatic stop-start		15	%								
Adjustable AESS + fuel operated heater		15	%								
Driveline			_								
6x2 axle configuration ^b		30	0%			Х				Х	
Baseline axle efficiency (93.5%)		20	0%								
Axle efficiency with low friction lubricants (95.4%)		80)%			X					
Advanced axle efficiency (97%)										Х	
Tire rolling resistance ^c	Steer	Dri	ive	Trailer	Steer	Drive	e Traile	r	Steer	Drive	Trailer
Baseline	5%	59	%								
Level 1	10%	10)%								
Level 2	50%	50	0%	5%							
Level 3	35%	35	5%		X	X	Х				
Level 4				95%							
Level 5									Х	Х	×
Level 5 Model input (C,,)	5.6 kg/t	5.8 A	kg/t	4.8 kg/t	4.9 kg/t	5.0 kg	/t 5.1 kg,	⁄t	X 4.0 kg/t	X 4.1 kg/t	
	5.6 kg/t	5.8 F 5.3 F		4.8 kg/t	4.9 kg/t	5.0 kg 5.0 kg		/t			4.2 kg/t
Model input (C _n)	5.6 kg/t Tractor	5.3 k		4.8 kg/t Trailer	4.9 kg/t Tractor	5.0 kg		/t		4.1 kg/t 4.1 kg/t	4.2 kg/t
Model input (C") Vehicle weighted-average C"		5.3 k				5.0 kg	/t	/t	4.0 kg/t	4.1 kg/t 4.1 kg/t	4.2 kg/t
Model input (C,,) Vehicle weighted-average C,, Aerodynamics	Tractor	5.3 k				5.0 kg	/t	/t	4.0 kg/t	4.1 kg/t 4.1 kg/t	4.2 kg/t
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III	Tractor 20%	5.3 k				5.0 kg	/t	/t	4.0 kg/t	4.1 kg/t 4.1 kg/t	4.2 kg/t
Model input (C _{rr}) Vehicle weighted-average C _{rr} Aerodynamics Bin III Bin IV	Tractor 20% 30%	5.3 k		Trailer	Tractor	5.0 kg	/t	/t	4.0 kg/t	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin IV Bin V	Tractor 20% 30%	5.3 k		Trailer 30%	Tractor	5.0 kg	/t Trailer	/t	4.0 kg/t Tractor	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin IV Bin V Bin V Bin VI Bin VII	Tractor 20% 30%	5.3 4	kg/t	Trailer 30%	Tractor	5.0 kg	/t Trailer		4.0 kg/t Tractor	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin IV Bin V Bin V Bin VI Bin VI Bin VII Model input (C,A)	Tractor 20% 30% 50%	5.3 4	kg/t	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin IV Bin V Bin V Bin VI Bin VI Bin VII Model input (C,A) Weight reduction	Tractor 20% 30% 50%	5.3 4	kg/t	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin IV Bin V Bin VI Bin VII Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs)	Tractor 20% 30% 50%	5.3 4	kg/t	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin V Bin VI Bin VII Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls	Tractor 20% 30% 50%	5.3 4	kg/t -1.	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin V Bin VI Bin VII Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control	Tractor 20% 30% 50%	5.3 4	kg/t -1.	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin V Bin VI Bin VII Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control	Tractor 20% 30% 50%	5.3 4	kg/t -1.	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin II Bin V Bin VI Bin VII Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control Advanced predictive cruise control	Tractor 20% 30% 50%	5.3 k 40	kg/t -1 0%	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t X	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin II Bin V Bin VI Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control High efficiency or electric A/C	Tractor 20% 30% 50%	5.3 F 40 30	kg/t -1 0%	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t X X	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin II Bin V Bin V Bin VI Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control Accessories High efficiency or electric A/C Improved accessories (2 kW load reduction)	Tractor 20% 30% 50%	5.3 k 40	kg/t -1 0%	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t X	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C,, Aerodynamics Bin III Bin V Bin VI Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control Accessories High efficiency or electric A/C Improved accessories (2 kW load reduction) Other technologies	Tractor 20% 30% 50%	5.3 k 40 30 30	-1 0%	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t X X	4.2 kg/t Trailer X
Model input (C,,) Vehicle weighted-average C, Aerodynamics Bin II Bin IV Bin V Bin VI Model input (C,A) Weight reduction Advanced lightweighting (2,700 lbs) Intelligent controls Predictive cruise control Advanced predictive cruise control Accessories High efficiency or electric A/C Improved accessories (2 kW load reduction)	Tractor 20% 30% 50%	5.3 F 40 30	-1 0%	Trailer 30% 70%	Tractor	5.0 kg	/t Trailer X		4.0 kg/t Tractor X	4.1 kg/t 4.1 kg/t X X	4.2 kg/t Trailer X

a Adoption rates of manual, automatic, automatic manual, and dual clutch transmission technologies do not add up to 100% in the Phase 2 rulemaking.

^b Includes 300-pound weight reduction.
 ^c In Phase 2, tire rolling resistance values are defined through Level 3 for steer and drive tires and Level 4 for trailer tires. Level 2 tires are the baseline for box trailers, while the baseline for steer and drive tires is named explicitly.

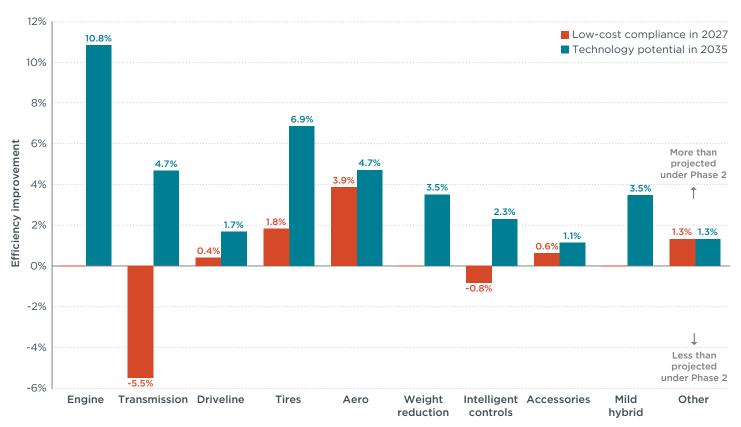


Figure 2. Tractor-trailer efficiency improvements by technology area for low-cost compliance in 2027 and technology potential in 2035, relative to Phase 2 standards.

Low-cost compliance in model year 2027

In an earlier cost analysis of the Phase 2 rulemaking, we identified an aero-focused technology package that delivered the lowest compliance costs for a Class 8 high-roof sleeper cab in model year 2027. However, this package included the most advanced aerodynamic technologies considered in the Phase 2 rulemaking for both tractors and trailers, corresponding to an aerodynamic drag area of 2.1 m², which may not be realistic. For this analysis we choose the second most cost-effective technology package, a tire-focused compliance strategy that included Level 3 tires and automatic tire inflation systems for both tractors and trailers. For trailers, the package also included Bin VI aerodynamics. For tractors, it included Bin V aerodynamics, a 6x2 axle configuration, top gear direct drive, a tamper-proof automatic engine shutdown system (AESS), and improved accessories. For the 6x2 configuration, we assume a weight reduction of 300 pounds. We additionally include axle efficiency improvements to achieve compliance in our simulations. This combined tractor-trailer technology package corresponds to a 6% reduction in the vehicle weighted-average tire rolling resistance coefficient compared to the adoption-weighted Phase 2 standard. With no adoption of more advanced transmission technologies, this technology area offers less efficiency improvement than projected under the standard. Collectively, this low-cost technology package delivers 56.7 gCO₃/ton-mi, an overcompliance of 1.8% in reference to our combined Phase 2 tractor-trailer standard for model year 2027.

Technology potential in model year 2035

Beyond model year 2027, we anticipate improvements in engine efficiency to achieve 55% peak brake thermal efficiency (BTE) for the Class 8 tractor-trailer, which has long

been a target for the U.S. SuperTruck program and has been demonstrated by at least one of the SuperTruck 2 teams (Heavy Duty Trucking Staff, 2021). The largest engine efficiency gains are associated with advanced waste heat recovery systems.

We also include dual clutch transmission technology, which enables enhanced enginetransmission integration and further engine downspeeding compared to an automated manual transmission. In GEM, we assume that efficiency savings from enhanced power train integration are similar for both transmission types but employ a lower drive axle ratio to simulate additional downspeeding potential for dual clutch transmissions. We optimize downspeeding for fuel savings while maintaining engine performance, such that the speed-trace remains within 2 mph for more than 90% of the cycle time, as in previous ICCT work (Delgado & Lutsey, 2015). We find that 15% downspeeding from the model year 2027 standard delivers 1.9% fuel savings when paired with the advanced road load technologies outlined below. With top gear direct drive, this translates to a drive axle ratio of 1.96.

Dual clutch transmission technology also enables engine downsizing by reducing the torque reserve needed. Engine downsizing can improve vehicle efficiency by shifting engine operation toward a more efficient region, which we model in GEM by downscaling the engine map. Using the same performance criteria as above, we find that 10% engine downsizing maximizes fuel savings when paired with 15% downspeeding and the advanced road load technologies outlined below. We do not include any weight reduction associated with engine downsizing.

Other drivetrain technologies include improved transmission gear and axle efficiencies. We assume full adoption of transmission gear efficiency improvements considered in the Phase 2 rulemaking. We anticipate improvements in axle efficiency up to 97%, which could be achieved with advanced low viscosity lubricants.

As is being demonstrated by the SuperTruck 2 teams, advances in road load technologies—including tires, aerodynamics, and lightweighting—have the potential to deliver significant efficiency gains beyond Phase 2. We assume continued development of low rolling resistance tire technology out to 2035, with the vehicle weighted-average rolling resistance coefficient falling to 4.1 kilograms per tonne (kg/t), 23% lower than assumed in the combined tractor-trailer standards in 2027. This aligns with input from key industry stakeholders, SuperTruck 2 achievements, and previous ICCT analysis. For tractor-only technology potential, we assume GEM default trailer tire rolling resistance of 6 kg/t, bringing the weighted average to 4.9 kg/t.

Aerodynamic drag areas as low as 3.1 m² were reported as part of the SuperTruck 1 program and below 3.0 m² in SuperTruck 2 (National Academies of Sciences, Engineering, and Medicine, 2020; U.S. Department of Energy, Office of Energy Efficiency and Renewable Energy, n.d.-b). However, some of the aerodynamic improvements demonstrated in the SuperTruck program are possible due to the permanent pairing of the tractor and trailer, and we conservatively estimate a higher drag area of 3.4 m², or a drag coefficient of 0.33. This is roughly equivalent to the second-most advanced tractor aerodynamic bin and a trailer with side skirts and a boat tail. For tractor-only technology potential, we assume GEM default trailer aerodynamics, which raises aerodynamic drag by 0.7 m² compared to the combined tractor-trailer potential.

The Phase 2 tractor-trailer standards were not predicated on vehicle weight reduction or lightweighting. However, weight reductions of more than 4,000 pounds have

been achieved by SuperTruck 1 and 2 project teams (National Academies of Sciences, Engineering, and Medicine, 2020; U.S. Department of Energy, Office of Energy Efficiency and Renewable Energy, n.d.-a). Several studies have reported fuel economy improvements ranging from 0.5% to 1% per 1,000-pound weight reduction for Class 8 tractor-trailers (National Academies of Sciences, Engineering, and Medicine, 2020; North American Council for Freight Efficiency, 2021). We model a total tractor-trailer weight reduction of 3,000 pounds, or a 9% reduction from the default GEM curb weight. This corresponds to a weight reduction of 2,700 pounds when combined with a 6x2 axle configuration and could be achieved with a shorter sleeper cab and frame, wide-base trailer tires, and the use of some aluminum components and other lightweight materials throughout the tractor and trailer. Since GEM assigns one-third of the total weight reduction to increased payload, these weight savings improve freight efficiency (i.e., gal/1000 ton-mi) by 1.3% per 1,000 pounds in our simulations. If we consider that the total vehicle weight is only reduced by two-thirds of the 2,700 pounds applied, fuel economy improves by 0.7% per 1,000 pounds of realized weight reduction compared to 0.4% per 1,000 pounds of applied weight reduction. For tractor-only technology potential, we remove 1,000 pounds of weight reduction, attributing this portion to trailer technologies.

Improvements in several other technologies may deliver efficiency improvements by 2035. We anticipate significant advances in predictive cruise control technology, with enhancements such as traffic prediction and cooperative control. Estimated efficiency improvements for these enhancements are as high as 13% but depend strongly on driving conditions: for cooperative control, much smaller efficiency improvements are associated with long separation distances, speed variation, and curved roads. (Zhai et al. 2020, Jia et al. 2021, and McAuliffe et al. 2018). We conservatively model an additional 1% efficiency gain beyond the 2% gain pre-defined in the Phase 2 rulemaking.

The electrification of accessories, known as e-accessories, is increasingly feasible with the adoption of 48-volt electrical systems. All five SuperTruck 2 project teams adopted 48-volt systems, enabling the electrification of power steering, coolant pumps, cooling fans, A/C compressors, and auxiliary power units (U.S. Department of Energy, Office of Energy Efficiency and Renewable Energy, n.d.-b). Efficiency improvements up to 1% each have been reported for electric coolant pumps and power steering (Kiesenhofer, 2021; National Academies of Sciences, Engineering, and Medicine, 2020). We conservatively model a total 1.5% efficiency gain from the baseline GEM configuration, or 1.1% compared to the Phase 2 standard, corresponding to full adoption of high efficiency A/C compressors and an additional 2 kW load reduction.

Mild hybrid technology has seen increasing adoption in several heavy-duty vehicle segments, led by transit bus operations and smaller urban delivery trucks. For tractor-trailers, hybridization primarily offers efficiency savings through the recovery of braking losses, known as regenerative braking. Several SuperTruck 2 project teams adopted mild hybrid systems, providing energy storage in addition to enabling further accessory electrification, with battery capacities up to 14 kWh (U.S. Department of Energy, Office of Energy Efficiency and Renewable Energy, n.d.-a, n.d.-b). Lombardi et al. (2020) modeled efficiency improvements upwards of 20% for a Class 8 tractor-trailer with a 28-kWh battery at 100 kW nominal power, over several drive cycles including the full FIGE and HHDDT cycles. In this analysis, we assume a PO hybrid with a 10-kWh battery and 50 kW motor nominal power, allowing for a 60% state-of-charge swing. We estimate efficiency gains of 4.0% from regenerative braking, based on Amesim simulations weighted over the three GEM drive cycles. This estimate decreases

slightly after accounting for the weight of the hybrid system, which we assume adds 500 pounds to the total vehicle weight.

VOCATIONAL VEHICLES

The technology adoption rates for the Phase 2 standard in model year 2027 are shown in Table 4, alongside the technology packages assumed for low-cost compliance and our estimate of the technology potential out to 2035. These assumptions are described in more detail below. Figure 3 shows efficiency improvements by technology area in each modeling scenario, relative to the Phase 2 standard. **Table 4.** Class 6–7 multipurpose vocational vehicle technologies and adoption rates projected under the Phase 2 standard, compared to low-cost compliance in 2027 and our assumed technology potential in 2035. Technologies not considered in the Phase 2 rulemaking are highlighted in yellow. Tire rolling resistance levels and aerodynamics bins are listed in Table A1 in the Appendix.

	Dhace 2 stan	dard in 2027	Low-cost com	oliance in 2027	Technology po	tantial in 2075	
Engine	Plidse 2 stall				Technology po		
		<		<			
2027 compliant engine (43% peak BTE) Advanced engine (49% peak BTE)	/	\	, 	^	Х		
Transmission					^		
Automatic		<		κ	×		
2 additional gears (8-speed))%	,	^	^		
Lock-up in 3 rd)%					
Lock-up in 1 st)%					
Advanced shift strategy)%		<			
1% gear efficiency improvement	62		, ,	^			
Bolt-on hybrid	6						
Integrated mild hybrid with stop-start		%			X		
	0	70			~		
Idle reduction)%		κ			
Stop-start)%		\ 	(part of mi	ld hybrid)	
Automatic engine shutdown)%		<	(part of fill X		
Driveline	/0	776	,	х 	~		
4x2 axle configuration		<		<	×		
5.29 drive axle ratio		<		χ <	X		
Baseline axle efficiency (89%))%		` <	~		
Axle efficiency with low friction lubricants (93%))%		X			
Advanced axle efficiency (97%)					×		
Tire rolling resistance	Steer	Drive	Steer	Drive	Steer	Drive	
Level 3v		100%					
Level 5v	100%		Х	Х			
Level 7v ^a					X	Х	
Model input (C")	6.2 kg/t	6.9 kg/t	6.2 kg/t	6.2 kg/t	4.8 kg/t	4.8 kg/t	
Vehicle weighted-average C _{rr}	6.7	kg/t	6.2	kg/t	4.8 k	:g/t	
Aerodynamics							
Side skirts	0'	%			×		
Nose cone	0	%			×		
Model input (C_A)	5.4	<i>m</i> ²	5.4	<i>m</i> ²	4.8	<i>m</i> ²	
Weight reduction							
Aluminum wheels (150 lbs)	50)%			×		
Advanced lightweighting (1,100 lbs)					×		
Accessories							
Improved accessories (0.4 kW load reduction)	15	%					
Advanced accessories (0.8 kW load reduction)					×		
Other technologies							
Tire pressure monitoring system	80)%	2	<	×		

^a Phase 2 defined tire rolling resistance only through Level 5v.

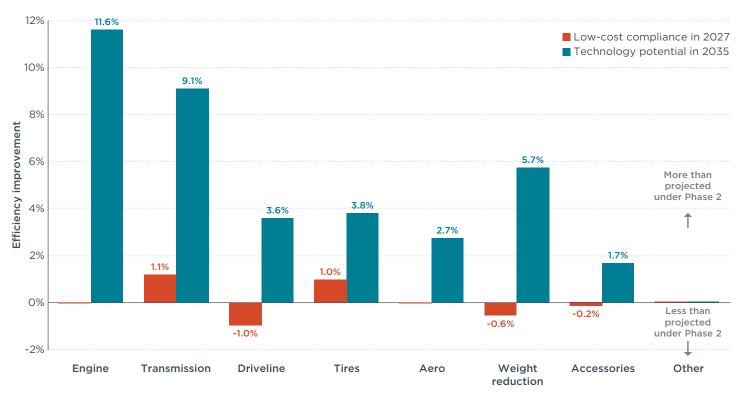


Figure 3. Vocational vehicle efficiency improvements by technology area for low-cost compliance in 2027 and technology potential in 2035, relative to the Phase 2 standard.

Lowest cost compliance in model year 2027

In an earlier cost analysis of the Phase 2 rulemaking, we identified a tire-focused technology package that delivered the lowest compliance costs for a Class 6-7 multipurpose vocational vehicle in model year 2027. This package included Level 5v tires and a tire pressure monitoring system as well as advanced shift strategy, automatic engine shutdown, and neutral idle technology. The package additionally included early torque converter lockup, which we exclude to reduce overcompliance in this analysis. This technology package corresponds to a 7.3% reduction in the vehicle weighted-average tire rolling resistance coefficient compared to the adoption-weighted Phase 2 standard. With no adoption of low friction lubricants, axle efficiency decreases by roughly 1 percentage point. Collectively, this low-cost technology package delivers 233 gCO₂/ton-mi, an overcompliance of 0.7% compared to the respective Phase 2 standard for model year 2027.

Technology potential in model year 2035

Beyond model year 2027, we anticipate further improvements in engine efficiency up to 49% peak BTE, comparable to the relative improvement we assume for tractortrailers from model year 2027 to 2035. Achates Power recently developed a near-50% BTE engine targeting Class 8 trucks that meets California's low-NOx standards and has announced development of engine variants for medium-duty applications (Schreck, 2021). We do not consider automated manual transmissions, in alignment with the agencies who could not determine "a predictable level of improvement" over an automatic transmission (U.S. Environmental Protection Agency & U.S. DOT, 2016). As for the Class 8 tractor-trailer, we assume improvements in axle efficiency up to 97%. Low rolling resistance tires and lightweighting are key road load reduction technologies for vocational vehicles. We anticipate advances in low rolling resistance tires beyond Level 5v, with the vehicle weighted-average rolling resistance coefficient falling to 4.8 kg/t, 28% lower than the adoption-weighted Phase 2 standard in model year 2027. This is less ambitious than that found in other ICCT analysis but represents a 3% annual reduction from the coefficient in our low-cost compliance vehicle in 2027 (Delgado et al., 2017).

Lightweighting generally delivers greater efficiency improvements for vocational vehicles than for tractor-trailers because their transient operations benefit more from curb weight reductions. Vocational vehicles are also expected to have more weightsensitive payloads, and this is reflected in GEM, which assigns half of any simulated weight savings to payload increases compared to only one-third for tractor-trailers. Literature on lightweighting specific to medium-duty trucks is sparse, but two studies reported fuel economy improvements of 3-4% per 1,000-pound weight reduction for Class 5-7 trucks (Environmental Defense Fund, 2010; Wang et al., 2016). We model a total weight reduction of 1,250 pounds, or a 9% reduction from the default GEM curb weight. This corresponds to an additional 1,100 pounds of lightweighting beyond the aluminum wheels considered under Phase 2 and could be achieved with various lightweight material substitutes, such as for the frame, axle hubs, and driveshaft. In our simulations, these weight savings improve freight efficiency (i.e., gal/1000 ton-mi) by 4.9% per 1,000 pounds. If we consider that the total vehicle weight is only reduced by one-half of the 1,250 pounds applied, fuel economy improves by 1.5% per 1,000 pounds of realized weight reduction compared to 0.7% per 1,000 pounds of applied weight reduction.

Aerodynamic improvements deliver fewer benefits for vocational vehicles than for tractor-trailers, and therefore tend to be less cost-effective. No adoption of aerodynamic technologies was projected under the Phase 2 standards. One study reported an 8% efficiency benefit for a Class 6 box truck when equipped with side skirts and a front fairing, or nose cone (Ragatz & Thornton, 2016). We model the same 0.6 m² decrease in aerodynamic drag area, corresponding to a drag coefficient of 0.89.

Accessory electrification has the potential to deliver significant fuel savings in medium-duty applications. In the Phase 2 rulemaking, electrification of power steering and A/C compressors were assigned efficiency improvement values of 1% and 0.5%, respectively. The addition of high efficiency alternators and electric cooling fans could further increase accessory savings. We model a 2% efficiency gain from the baseline GEM configuration, corresponding to a total load reduction of 0.8 kW. Vocational vehicles with higher accessory loads may have larger potential improvement, which is not reflected in the default GEM configuration.

Transmission-enabled engine downspeeding and downsizing are less relevant for multipurpose vocational vehicles, which have more variable drive cycles and log fewer highway miles than long-haul trucks. In the Phase 2 rulemaking, the agencies considered several technologies for improving automatic transmissions in vocational vehicles, such as adding two more gears and enhancing driveline integration with the use of advanced shifting strategies and torque converter lockup in 1st gear instead of 3rd. However, an integrated mild hybrid with a P2 configuration—positioned between the engine and transmission—either precludes or incorporates many of the efficiency gains from these individual technologies.

For vocational vehicles, mild hybridization typically offers the largest efficiency savings through its stop-start functionality. Efficiency benefits also accrue from regenerative braking, and some may also incorporate torque assist during launch. A recent study reported a 22% efficiency improvement for a Class 6-7 urban vocational truck utilizing a mild hybrid system with stop-start (Dahodwala et al., 2021). In this analysis, we assume a 17.4% efficiency improvement for multipurpose vocational vehicles, the same as calculated by the agencies in the Phase 2 rulemaking. Estimated efficiency benefits from our own simulations in Amesim, weighted over the three GEM drive cycles, are roughly comparable. GEM does not provide a mechanism to simulate increases in vehicle weight that do not offset lightweighting, and we align with the agencies in not considering this as part of the integrated mild hybrid system.

TECHNOLOGY COST-EFFECTIVENESS

For each of the individual technology improvements described in the previous section, we assess the costs and cost-effectiveness from low-cost compliance in 2027 to the technology potential in model year 2035. We define a given technology's cost-effectiveness as its cost (in 2020 U.S. dollars) per percent reduction in fuel consumption, as measured in simulation. Unless otherwise noted, all technology costs in 2035 are estimated based on cost data in the Phase 2 rulemaking documents (U.S. Environmental Protection Agency & U.S. DOT, 2016).

TRACTOR-TRAILERS

When available, the cost data for tractor-trailer technologies are based on the Phase 2 Regulatory Impact Analysis, converted from 2013 to 2020 dollars. For those fuelsaving technologies not explicitly included in the Phase 2 rulemaking, our methodology and cost estimates are summarized in Table 5, with costs rounded to the nearest ten dollars. The methodology is described in more detail below.

Table 5. Marginal costs and methodology for tractor-trailer technologies in 2035 compared to the low-cost compliance vehicle in2027. All other technology costs are sourced from the Phase 2 Regulatory Impact Analysis.

	Marginal cost relative to low- cost compliance in 2027 (2020\$)	Methodology	Туре
Engine efficiency	\$8,200	Cost = [cost per % reduction, MY 2027] * 2 * 10.8%	Extended from Phase 2
Engine downsizing	-\$690	Cost = [cost savings for 10% downsizing]	Adapted from Meszler et al. (2015)
Axle efficiency	\$380	Cost = [cost of improvement from 93% to 95% efficiency] * 2	Extended from Phase 2
Low rolling resistance tires	\$310	Cost = [cost of most advanced tire level in Phase 2] * 1.5	Extended from Phase 2
Lightweighting	\$5,130	Cost = 2,700 lbs * ([Low cost per lb. for 3,240-lb. weight reduction] + [High cost per lb. for 3,240-lb. weight reduction]) / 2	Adapted from Meszler et al. (2015)
Advanced predictive cruise control	\$1,680	Cost = [cost of predictive cruise control] * 2	Extended from Phase 2
Mild hybridization	\$14,300	Cost = [cost of mild hybrid system for heavy heavy-duty vocational vehicle] * 1.1	Adapted from Phase 2 vocational cost

There are no cost estimates in the Phase 2 rulemaking for an engine that achieves 55% peak BTE. To estimate the cost of these engine efficiency improvements, we draw on the cost per percent fuel consumption reduction for the model year 2027 engine, which was roughly \$350 per percent reduction. Efficiency improvements are expected to increase in cost as engines push up against thermodynamic limits, such that incremental improvements beyond model year 2027 would be more expensive on a cost per percent reduction basis. Based on conversations with the SuperTruck 2 project teams, there appears to be a large degree of uncertainty as to the cost of commercializing a 55% peak BTE engine. Given this uncertainty, we assume a two-fold increase in the model year 2027 cost per percent reduction achieved by the 55% peak BTE engine over the regulatory cycle yields roughly \$8,200. Figure A2 in the Appendix compares this cost per percent reduction in fuel consumption in 2035 to the cost estimate in 2017 and 2027 from the Phase 2 rulemaking.

Cost savings associated with engine downsizing are not included in the Phase 2 rulemaking, and we source these costs from Meszler et al. (2015). For improvements in axle efficiency up to 97%, we double the cost that the agencies estimated in the Phase 2 regulation to move from 93% to 95% efficiency.

We assume that a new tire technology bin is achieved for all tires by 2035, with costs that are 50% higher than the most advanced tire bin assumed in the Phase 2 rulemaking. For lightweighting, we estimate a per-pound cost based on the average of high- and low-cost scenarios for a 3,240-pound weight reduction in Meszler et al. (2015), multiplied by the 2,700 pounds applied in our analysis. For advances in predictive cruise control technology, we double the cost reported for predictive cruise control systems in the Phase 2 rulemaking.

We estimate the cost for a mild hybrid system for Class 8 tractor-trailers based on the agencies' cost estimates for Class 8 vocational vehicles, since hybridization was not considered in setting the stringency for tractor trucks in the Phase 2 regulation. Since tractor-trailers have more stringent durability requirements compared to vocational vehicles, we increase the cost by 10%.

Figure 4 shows the cumulative costs and percent reduction in fuel consumption as technologies are added to the vehicle in order of cost-effectiveness—i.e., technology areas are less cost-effective moving from left to right. Low rolling resistance tires are by far the most cost-effective technology area, with costs of about \$60 per percent reduction in fuel consumption. Axle efficiency improvements (including 6x2 axles), advanced predictive cruise control, and aerodynamics are next in the cost-effectiveness ranking and provide fuel savings at a cost of \$500 to \$600 per percent reduction. Engine efficiency and accessory load reductions bring the total per-vehicle fuel savings to just over 20% at a cumulative cost of roughly \$11,700. Curb weight reduction of 2,700 pounds pushes the total fuel consumption down by another 3 percentage points. The next technology progression includes a dual clutch transmission, 15% engine downspeeding, 10% engine downsizing, and a diesel auxiliary power unit (including engine automatic shutoff) which bring overall efficiency improvements to roughly 31% at a cost of nearly \$22,000. A mild hybrid system is the least cost-effective technology included in our analysis and brings total fuel savings for the tractor-trailer to about 33% and total costs to roughly \$53,000.

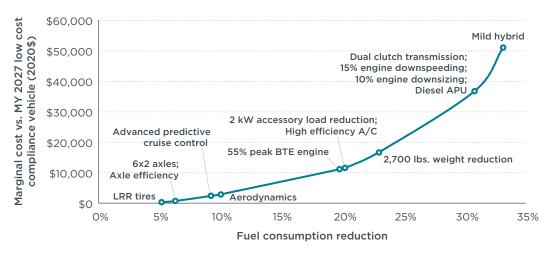


Figure 4. Cost curve of tractor-trailer efficiency technologies beyond the model year 2027 low-cost compliance Class 8 high-roof sleeper cab.

VOCATIONAL VEHICLES

Table 6 summarizes our methodology and cost estimates for fuel-saving technologies for multipurpose vocational vehicles. The methodology is described in more detail below. As for tractor-trailers, any technology costs not listed are sourced from the Phase 2 Regulatory Impact Analysis and costs are rounded to the nearest ten dollars.

Table 6. Marginal costs and methodology for Class 6-7 multipurpose vocational vehicle technologies in 2035 compared to the low-cost compliance vehicle in 2027. All other technology costs are sourced from the Phase 2 Regulatory Impact Analysis.

	Marginal cost relative to low- cost compliance in 2027 (2020\$)	Methodology	Туре
Engine efficiency	\$3,030	Cost = [cost per % reduction, MY 2027] * 2 * 11.6%	Extended from Phase 2
Axle efficiency	\$510	Cost = [cost of improvements from 90% to 93% efficiency] + [cost of tractor truck improvement from 93% to 97% efficiency]	Adapted from Phase 2 vocational and tractor truck costs
Low rolling resistance tires	\$150	Cost = [cost of most advanced tire level in Phase 2] * 2	Extended from Phase 2
Aerodynamics	\$930	Cost = [cost of side skirt for short van trailer] + [cost of nose cone]	Adapted from Phase 2 and NRC (2010)
Lightweighting	\$2,190	Cost = 1,250 * ([Low cost per lb. for 3,240-lb. weight reduction] + [High cost per lb. for 3,240-lb. weight reduction]) / 2	Adapted from Meszler et al. (2015)
Accessory load reduction	\$1,550	Cost = [cost for 0.4 kW load reduction] * 2	Extended from Phase 2

We estimate the costs of engine efficiency improvements using the same methodology as for the tractor truck engine. We again assume a two-fold increase in the cost per percent reduction in fuel consumption for the model year 2027 engine, which represents the complexity and added costs of pushing to higher peak BTE. Multiplying this cost per percent reduction by the 11.6% fuel consumption reduction achieved by the 49% peak BTE engine over the regulatory cycle yields roughly \$3,000.

For improvements in axle technology, the Phase 2 rulemaking includes cost estimates to move from 90% to 93% efficiency for vocational vehicles. We use our tractor truck estimate from this study to account for additional costs to increase from 93% to 97% efficiency.

As with the tractor truck, we assume a new rolling resistance tire technology bin, with costs that are double that of the most advanced tire bin assumed in the Phase 2 rulemaking. Aerodynamic advancements are not considered for vocational vehicles in setting the stringency of the standards in the Phase 2 regulation. As such, we develop an estimate for an 11% reduction in aerodynamic drag by adding the cost of side skirts for a short box-trailer in the Phase 2 rulemaking to the estimated cost of a nose cone for a medium-duty box truck (National Research Council, 2010). For lightweighting, we use the same per-pound cost estimate derived from Meszler et al. (2015), multiplied by the 1,250 pounds applied in our vocational analysis. Finally, we double the cost of a 0.4 kW reduction in accessory loads to estimate the cost for a 0.8 kW load reduction.

Figure 5 shows the cumulative costs and percent reduction in fuel use as technologies are added to the vehicle in order of cost-effectiveness, as in Figure 4. As with tractor-trailers, low rolling resistance tires are the most cost-effective technology area we considered, with costs of about \$40 per percent fuel consumption reduction. Axle efficiency improvements are also very cost-effective and provide efficiency

improvements at roughly \$100 per percent fuel consumption reduction. Advances in engine and aerodynamic technologies are clustered relatively closely, with each providing benefits at approximately \$300 per percent reduction. Together, these technologies push efficiency improvements to over 20% compared to the model year 2027 baseline at a cumulative cost of roughly \$4,700. At \$340 per percent reduction, lightweighting for the vocational vehicle is much more cost-effective than for the tractor-trailer, which we estimate to cost approximately \$1,500 per percent reduction. The addition of electrified and more efficient accessories, along with a hybrid-electric powertrain, brings overall fuel savings to 34% at a total cost of approximately \$17,400.

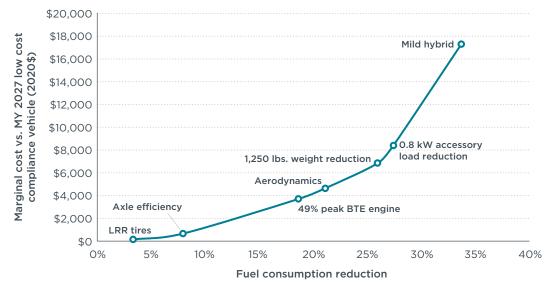


Figure 5. Cost curve of vocational vehicle efficiency technologies beyond the model year 2027 low-cost compliance Class 6-7 multipurpose vocational vehicle.

TECHNOLOGY PACKAGE RESULTS

We define several incremental technology packages for each vehicle based on deployment of technologies in order of cost-effectiveness, starting from the low-cost compliance scenario. For each of these packages, we derive the cumulative technology payback period using the cost estimates described in the previous section. Costs for individual technologies that make up each package are detailed in the Appendix, as well as a cost comparison to the Phase 2 standard in 2027.

Payback values for all technology packages are calculated using the same annual vehicle miles traveled as the agencies in the Phase 2 regulatory impact analysis. We also use 2035 diesel fuel prices from the 2021 Annual Energy Outlook (AEO)'s *Reference case* and a conservative 7% discount rate (U.S. Energy Information Administration, 2021). We additionally perform a sensitivity analysis with two bounding scenarios: (1) low fuel costs from AEO 2021 combined with a 10% discount rate and (2) high fuel costs from AEO 2021 with a 3% discount rate. The three AEO fuel price scenarios and payback results from this sensitivity analysis can be found in the Appendix.

TRACTOR-TRAILERS

Figure 6 shows vehicle efficiency improvements for each technology package compared to our combined Phase 2 tractor-trailer standard and low-cost compliance scenario in model year 2027. The payback period is shown relative to the low-cost compliance vehicle, which has compliance costs of approximately \$4,200 compared to the roughly \$15,800 that the agencies estimated as average compliance costs in model year 2027. The cumulative marginal costs and fuel consumption reductions for each incremental technology package are shown along with the two alternative payback period scenarios in Figure A3 in the Appendix.

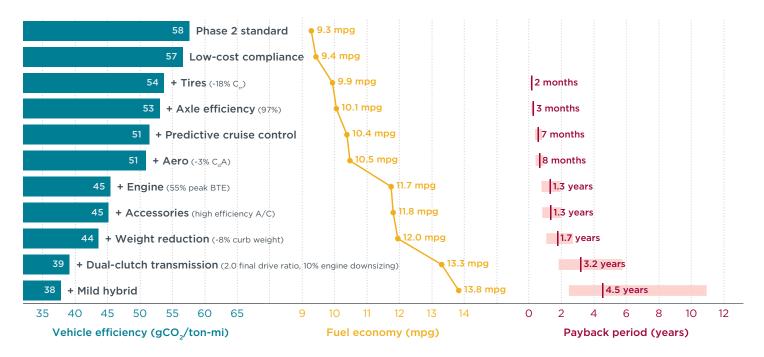


Figure 6. Vehicle efficiency, fuel economy, and payback period for incremental technology improvements from low-cost compliance with the Phase 2 standards for Class 8 high-roof sleeper cab tractor-trailers in model year 2027.

Beyond low-cost compliance with the Phase 2 standard, anticipated advances in tire rolling resistance would achieve the most cost-effective efficiency improvements. By reducing fuel use by more than 5% at a cost of roughly \$300, tire advances are expected to recoup upfront costs in around 2 months. Together with improvements in axle efficiency, predictive cruise control, and aerodynamics-all with payback periods of less than one year-we project a 1 mile per gallon (mpg) increase in fuel economy and a 10% vehicle efficiency improvement. Engine and transmission technologies achieve some of the largest efficiency improvements, with each technology area raising fuel economy by roughly 1.3 mpg. Engine efficiency improvements are much more cost-effective, however, at about one-third the price of the transmission technology package. Mild hybrid technology offers a smaller 0.5 mpg fuel economy improvement at about two-thirds the price of the transmission technology package. Optimization of mild hybrid technology and additional accessory electrification not considered in our analysis have the potential to increase the fuel savings and costeffectiveness of mild hybridization. In total, the efficiency technologies explored in this analysis deliver a 49% increase in fuel economy and a 34% decrease in per ton-mile CO₂ emissions from model year 2027 standards. This full technology potential has a marginal cost of \$52,900 compared to low-cost compliance scenario, or \$41,300 compared to the agencies' adoption-weighted compliance cost.

In both the Phase 1 and 2 regulations, the agencies set the stringency targets for tractor trucks such that the technology packages had payback values of two years or less. This two-year payback reflects the nature of the trucking market, in which a large percentage of fleets—particularly for-hire trucking companies—tend to have ownership cycles of four to six years. Taking the lower end of this range, a two-year payback would allow a fleet to recoup its investment in the first half of a vehicle's life and then receive a return on investment in the final two years of ownership. Excluding mild hybridization and transmission-enabled efficiency strategies like engine downspeeding and downsizing, all the technologies we modeled are projected to recoup costs within 2 years. At a marginal cost of \$16,800 compared to low-cost compliance with the Phase 2 standard, this technology package delivers a 2.7 mpg, or 29%, increase in fuel economy and a 24% decrease in per ton-mile CO_2 emissions from model year 2027 standards. A model year 2035 vehicle with these technologies is projected to achieve a fuel economy of 12 mpg, doubling the 6-mpg fuel economy baseline for model year 2010 assumed in the Phase 1 rulemaking.

Previous ICCT analysis of efficiency technologies for tractor-trailers identified the potential to achieve a fuel economy of 11.6 mpg over a real-world highway cycle and 12.3 mpg over a 65-mph cycle with variable speed by 2030. In Figure 7, we compare the latter, with a drive cycle that bears more resemblance to the three GEM drive cycles, to both the full and two-year payback technology potential for 2035 identified in this analysis. We also show the combined Phase 2 tractor-trailer standards in 2027 and the EPA's projection of the best tractor-trailer in 2027 (U.S. EPA, 2015). Efficiency technologies assumed in this best tractor-trailer are summarized in Table A5 in the Appendix and include engine efficiency improvements to 49.8% peak BTE, an automated manual transmission with direct drive, and a 6x2 axle configuration.

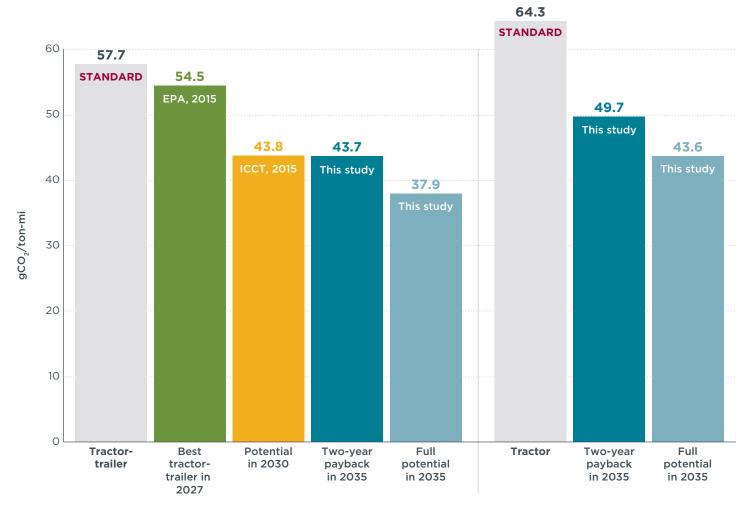


Figure 7. Tractor-trailer and tractor-only technology potential from this study compared to previous ICCT and EPA analysis, as well as Phase 2 standards. Values for fuel economy and payload can be found in the Appendix.

We separately compare tractor-only results from this analysis to the current Phase 2 tractor standard, given that Phase 2 trailer standards are currently suspended due to legal challenges from manufacturers (Motor & Equipment Manufacturers Association, n.d.). Our tractor-only simulations use the default GEM parameters for trailer tires and aerodynamics—namely 6 kg/t tire rolling resistance and -0.3 m² delta C_dA for trailer skirts—and exclude 1,000 pounds of lightweighting and trailer automatic tire inflation systems from the technology potential in 2035.

This comparison illustrates the untapped technology potential recognized by the EPA during the Phase 2 rulemaking process, with 6% lower per ton-mile CO_2 emissions than required under the combined tractor-trailer standards we simulated. It also shows how far the combined tractor-trailer results of our study go beyond previous ICCT analysis, with the potential for roughly 13% lower per-ton mile CO_2 emissions and 12% higher fuel economy. These results are not strictly comparable, however, given the use of a different vehicle simulation platform and different drive cycles in the earlier ICCT analysis. Still, our analysis simulates more substantial improvements in road load technology, including roughly 11% lower tire rolling resistance and roughly 7% lower aerodynamic drag area, as well as larger efficiency gains for mild hybrid technology

and the consideration of e-accessories and intelligent controls. Compared to the Phase 2 standard in 2027, our analysis indicates potential for 24% (two-year payback) and 34% (full potential) reduction from the combined tractor-trailer standard we simulate.

As evidenced by the difference between combined tractor-trailer and tractor-only simulations, trailer technologies significantly improve fuel economy and vehicle efficiency. Trailers have significant untapped potential for aerodynamics and lightweighting, which has been demonstrated by the SuperTruck program. In our simulations, the inclusion of a trailer boat tail, rolling resistance tires comparable to steer and drive tires, an automatic tire inflation system, and an additional 1,000 pounds of lightweighting deliver 13% efficiency benefit. However, even without trailer technologies, we estimate tractor-only technology improvements with less than a two-year payback period could deliver 23% lower per-ton mile CO₂ emissions by 2035 compared to the Phase 2 tractor standard in 2027. This corresponds to a 27% increase in fuel economy from 8.3 to 10.6 mpg.

VOCATIONAL VEHICLES

Technology package results for vocational vehicles are shown in Figure 8, in order of cost-effectiveness and with the payback period shown relative to the low-cost compliance scenario. This low-cost vehicle has compliance costs of approximately \$1,100 compared to the roughly \$3,100 that the agencies estimated as average compliance costs in model year 2027. As with the tractor-trailer, cumulative marginal costs, fuel consumption reductions, and the two alternative payback period scenarios are shown in Figure A5 in the Appendix.

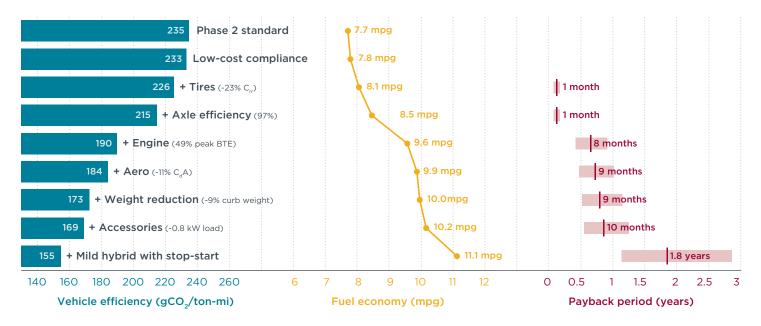


Figure 8. Vehicle efficiency, fuel economy, and payback period for incremental technology improvements from low-cost compliance with the Phase 2 standards for Class 6–7 multipurpose vocational vehicle standard in model year 2027.

The two most cost-effective technology improvements—low rolling resistance tires and axle efficiency—improve fuel economy by 0.7 mpg at an upfront cost of roughly \$650 relative to the low-cost compliance vehicle. At such low cost, these technologies are expected to recoup upfront costs within a month or two. Engine efficiency improvements are the next most cost-effective technology and contribute the largest efficiency improvements, increasing fuel economy by 1.1 mpg and decreasing per tonmile CO_2 emissions by nearly 12%. Mild hybridization is the most expensive technology we considered but offers significant fuel savings of 1 mpg, such that the cumulative payback period still falls within two years under the median cost scenario (7% discount rate, reference diesel cost).

Excluding mild hybrid technology, all the technologies we modeled are projected to recoup costs within 1 year in the median cost scenario. At a marginal cost of \$8,500 compared to low-cost compliance with the Phase 2 standard, this technology package delivers a 2.5 mpg, or 32%, increase in fuel economy and a 28% reduction in per ton-mile CO_2 emissions from the model year 2027 standard. Adding mild hybrid technology brings the total cost to \$17,400 compared to low-cost compliance scenario, or \$19,400 compared to the adoption-weighted Phase 2 standards. We project this full technology package to deliver a 44% increase in fuel economy and a 34% decrease in per ton-mile CO_2 emissions from model year 2027 standards. A model year 2035 vehicle with these technologies is projected to achieve a fuel economy of 11.1 mpg, which is on par with cost-effective (i.e., two-year payback) tractor truck fuel economy when trailer technologies are excluded.

CONCLUSIONS

Driven by greenhouse gas emissions regulations, heavy-duty vehicles have become increasingly fuel efficient over the last decade. In this analysis, we identified the potential for further efficiency improvements beyond 2027, the last model year of the Phase 2 standards, and out to 2035. We focused on two representative vehicle segments, a Class 8 high-roof sleeper cab and a Class 6–7 multipurpose vocational vehicle. We summarize key takeaways below.

- » Tractor-trailer efficiency technologies could cost-effectively reduce per tonmile CO₂ emissions by 24% from the Phase 2 standard. This corresponds to a 29% improvement in fuel economy to 12 mpg. By definition, this cost-effective technology package would recoup upfront costs in less than 2 years. We estimate a marginal cost of \$16,800 from the low-cost compliance scenario, or \$5,200 from the agencies' average compliance cost with Phase 2 in 2027.
- The full potential of tractor-trailer technologies could further reduce per tonmile CO₂ emissions by 10 percentage points, to 34% below the Phase 2 standard. Beyond the cost-effective technology package, full potential includes mild hybridization and transmission-enabled strategies like engine downspeeding and downsizing, which could increase fuel economy to 13.8 mpg. This adds a marginal cost of \$24,100 onto the cost-effective package, with a full cost of \$29,300 compared to the agencies' Phase 2 compliance costs. We estimate it would require nearly 5 years to recoup the upfront costs of this full technology package.
- » Estimated per ton-mile CO₂ emissions for tractors are 12-13% higher without trailer technologies. This reduces efficiency gains by 10 percentage points, to 14% and 24% for cost-effective and full technology packages, respectively. Marginal costs are reduced by \$2,000, such that trailer technologies would cost roughly \$200 per percent reduction in fuel consumption compared to roughly \$800 for engine efficiency improvements.
- All the efficiency technologies we considered for vocational vehicles would recoup costs in under two years and could reduce per ton-mile CO₂ emissions by 34% from the Phase 2 standard. This corresponds to a 44% improvement in fuel economy. We estimate a marginal cost of \$17,400 from the low-cost compliance scenario, or \$15,400 from the agencies' average compliance cost with Phase 2 in 2027.
- » Engine efficiency improvements deliver the largest efficiency benefits for both vehicle segments. Low rolling resistance tires, idle reduction technologies, and tractor-trailer aerodynamic improvements are also substantial, but we assume some of these advances are already deployed to achieve low-cost compliance in model year 2027.
- » Low rolling resistance tires continue to offer the most cost-effective efficiency benefits; aerodynamics, engine efficiency, and axle efficiency also deliver costeffective fuel savings for both vehicle segments. This parallels previous ICCT analysis, which showed Phase 2 standards could be met most cost-effectively through the adoption of low rolling resistance tires, advanced aerodynamics, and engine efficiency improvements (Sharpe et al., 2016, 2018).

The long lifetime of heavy-duty vehicles means that many internal combustion engine trucks sold in 2035 could still be on the road in 2050. Current Phase 2 standards are expected to continue to improve fuel economy and decrease per ton-mile CO_2

emissions through model year 2027. With anticipated advances in vehicle efficiency technology, our analysis shows that substantial and cost-effective efficiency improvements could still be made beyond current standards.

While this analysis focused specifically on diesel-powered vehicles, zero-emission heavy-duty vehicles also have a vital role to play in decreasing fuel use and greenhouse gas emissions. In future work, we aim to explore how zero-emission vehicles can be integrated into the stringency requirements in the next phase of greenhouse gas emissions standards for commercial truck and buses. For the United States and other countries to achieve ambitious climate targets for the transportation sector by mid-century, it is critically important to accelerate the deployment of zero-emission vehicles and to ensure that the last generations of internal combustion vehicles are as fuel-efficient and low-emitting as possible.

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APPENDIX

Table A1. Tire rolling resistance levels and aerodynamic bins for high-roof sleeper cab tractor-trailers and vocational vehicles. Technology levels extending beyond the Phase 2 rulemaking are highlighted in yellow.

Tractor-trailers					
Tire rolling resistance (C _{rr} , kg/t)	Steer	Dri	ve	Trailer	
Baseline	7.8	8	.1	_	
Level 1	6.6	6.	9	6.5	
Level 2	5.7	e	5	6	
Level 3	4.9	5	5	5.1	
Level 4	4.3	4.	5	4.7	
Level 5	4.0	4	.1	4.2	
Aerodynamics (C _d A, m ²)	Tracto	r	Tra	iler delta	
Bin I	≥6.9			0	
Bin II	6.3-6.8	3		0.1	
Bin III	5.7-6.2			0.4	
Bin IV	5.2-5.6	i		0.7	
Bin V	4.7-5.1		1		
Bin VI	4.2-4.6	5		1.4	
Bin VII	≤4.1			1.8	
Vocational vehicles					
Tire rolling resistance (C _{rr} , kg/t)					
Level 1v		7.5	-8.1		
Level 2v		7.0-7	7.49		
Level 3v		6.6-0	5.99		
Level 4v		6.3-0	6.59		
Level 5v		5.8-0	5.29		
Level 6v		5.2-	5.79		
Level 7v		4.7-	5.19		
Aerodynamics (C _d A, m ²)					
Skirt		-0	.3		
Nose cone		-0	.3		

Table A2. Model year 2010 baseline used in the Phase 1 rulemaking. Unlike Phase 2, the vocational vehicle baseline is not specific to an urban, regional, or multipurpose duty cycle.

	Class 8 high-roof sleeper cab	Class 6-7 vocational vehicle
Engine	45% peak BTE	40% peak BTE
Transmission	10-speed manual with direct drive	6-speed manual
Driveline	6x4 configuration 2.64 drive axle ratio 93.5% axle efficiency	4x2 configuration 3.36 drive axle ratio GEM default axle efficiency
Tire rolling resistance	7.2 kg/t weighted average	9 kg/t weighted average
Aerodynamics	7.3 m² C _d A	5.4 m² C _d A
Accessories	1.35 kW load	1.3 kW load

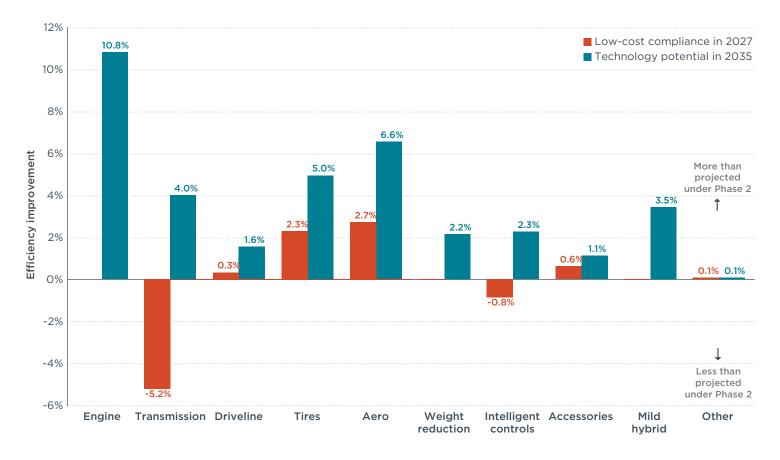


Figure A1. Vehicle efficiency improvements by technology area relative to the Phase 2 tractor standard, for low-cost compliance in 2027 and technology potential out to 2035. Transmission includes transmission-enabled downspeeding and downsizing, as well as idle reduction technologies; other includes tire pressure monitoring systems.

Table A3. Class 8 high roof sleep cab tractor technology adoption rates and costs for the Phase 2 model year 2027 standard, the low-cost compliance vehicle in model year 2027, and 2035 technology potential.

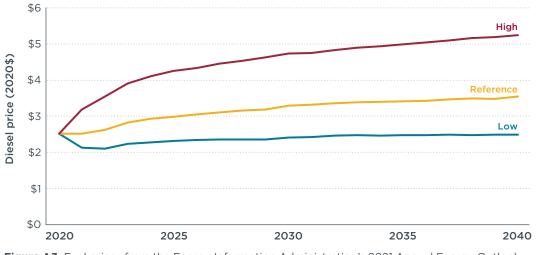
/							Ad	option ra	ites							Packag	e costs (2	2020\$)									
		hnology ((2020\$)	cost	MY 2	2027 sta	ndard	MY 2	2027 low ompliance	-cost	MY 20	035 techr potential		MY 2	027 star	dard		027 low-			35 techr potential							
Engine																											
2027 compliant engine (49% peak BTE)			\$1,726		100%			100%							\$1,726			\$1,726			\$0						
2027 compliant engine + WHR (50% peak BTE)			\$5,751												\$0)		\$0	0		\$0						
Advanced engine (55% peak BTE)			\$8,198								100%				\$0		\$C				\$9,933						
15% engine downsizing			-\$685								100%			\$0				\$0			-\$685						
Transmission																											
Automatic (with neutral idle)			\$13,347	30%									\$4,004			\$0		\$0			\$0						
Automated manual			\$4,212		50%										\$2,106			\$0			\$0						
Dual clutch 1% gear efficiency			\$12,656		10%						100%				\$1,445			\$0			\$14,453						
improvement			\$292		70% 50%			100%			100%				\$204 \$0			\$0 \$0			\$292 \$0						
Top gear direct drive Driveline			\$0		50%			100%			100%				\$0			\$0			\$U						
6x2 axle configuration			\$190		30%			100%			100%				\$57			\$190			\$190						
2.31 final drive ratio baseline					100%										\$0			\$0			\$0						
2.26 final drive ratio														\$0			\$0			\$0							
2.08 final drive ratio											100%			\$0				\$0			\$0						
Baseline axle efficiency (93.5%)					20%										\$0			\$0			\$0						
Axle efficiency with low friction lubricants (95.4%)			\$190		80%										\$152			\$0			\$0						
Improved axle efficiency (96%)			\$285												\$0			\$0			\$0						
Advanced axle efficiency (97%)			\$380								100%			\$0		\$0 \$0		\$0		\$0			\$380				
Tire rolling resistance	Steer	Drive	Trailer	Steer	Drive	Trailer	Steer	Drive	Trailer	Steer	Drive	Trailer	Steer	Drive	Trailer	Steer	Drive	Trailer	Steer	Drive	Trailer						
Baseline	\$0	\$0	\$0	5%	5%								\$0	\$0	\$0	\$0	\$0	\$0	\$0	\$0	\$0						
Level 1 Level 2	\$43 \$49	\$172 \$198	\$174 \$201	10% 50%	10% 50%	5%							(\$26) \$15	(\$103) \$59	(\$17)	(\$30)	(\$120)	(\$17)	(\$30)	(\$120) (\$40)	(\$17)						
Level 3	\$56	\$223	\$201	35%	35%	376	100%	100%	100%				\$20	\$78	(\$171) \$0	(\$10) \$56	(\$40) \$223	(\$181) \$227	(\$10) \$0	(\$40)	(\$181) \$0						
Level 4	\$75	\$295	\$227	5570	3370	95%	10070	10070	100%				\$0	\$0	\$215	\$0	\$0	\$0	\$0	\$0	\$0						
Level 5	\$105	\$413	\$295							100%	100%	100%	\$0	\$0	\$0	\$0	\$0	\$0	\$105	\$413	\$295						
Aerodynamics																											
Bin III			\$1,377		20%										(\$826)			(\$1,102)			(\$1,102)						
Bin IV Bin V		\$1,678 \$2,379		30% 50%				100%							\$336 \$1,189			(\$168)			(\$168) \$0						
Bin VI			\$2,893		50%			100%			100%				\$1,189			\$2,379			\$2,893						
Bin VII			\$3,405															\$0									
Idle reduction																											
Adjustable automatic engine shutdown system (AESS)			\$27		15%			100%							\$4			\$27			\$0						
Adjustable AESS + diesel auxiliary power unit (APU)			\$7,724		40%						100%				\$3,090			\$0			\$7,724						
Adjustable AESS + battery APU			\$4,944	15%		15%		15%		15%		15%									\$742			\$0			\$0
Adjustable AESS + automatic stop-start			\$1,481		15%										\$222			\$0			\$0						
Adjustable AESS + fuel operated heater			\$860 15%																\$129			\$0			\$0		
Intelligent controls																											
Predictive cruise control			\$837		40%										\$335			\$0			\$0						
Advanced predictive cruise control			\$1,675								100%				\$0			\$0			\$1,675						
Accessories																											
High efficiency or electric A/C			\$166		30%						100%				\$50			\$0			\$166						
E-accessories (1 kW load reduction)			\$133					100%							\$0			\$133			\$0						
Advanced e-accessories (2 kW load reduction)			\$267		30%						100%				\$80			\$0			\$267						
Other technologies Tire pressure			\$554		70%										\$388			\$0			\$0						
monitoring system Automatic tire			\$870					100%			100%				\$261			\$870			\$870						
inflation system					30%			100%													\$870						
Lightweighting			\$51ZZ												\$0												
Lightweighting (2,700 lbs) Mild hybridization (10-kWh battery)			\$5,133 \$14,300								100%				\$0			\$0 \$0			\$14,300						

Table A4. Class 6–7 multipurpose vocational vehicle technology adoption rates and costs for the Phase 2 model year 2027 standard, the low-cost compliance vehicle in model year 2027, and 2035 technology potential.

								ackage cos	sts (2020\$))																						
	Techn cost (2			2027 dard	low	2027 -cost oliance	techn	2035 Jology Antial	MY 2 stand		MY 2 low- compl	cost	MY 2 techno pote	ology																		
Engine																																
2027 compliant engine (43% peak BTE)		\$495	10	0%	10	0%				\$495		\$495		\$0																		
Improved engine (44% peak BTE)		\$739								\$0		\$0		\$0																		
Advanced engine (49% peak BTE)		\$3,033					10	0%		\$0	\$0		\$0		\$C		\$0		\$0		\$C		ç		\$(0		ç			\$3,657
Transmission																																
Automatic			10	0%	10	0%				\$0		\$0		\$0																		
Automated manual							10	0%		\$0		\$0		\$0																		
2 additional gears (8-speed)		\$517	20	0%						\$103		\$O		\$0																		
Lock-up in 3rd			50	0%						\$0		\$0		\$0																		
Lock-up in 1st		\$29	50	0%	10	0%				\$14		\$29		\$0																		
Advanced shift strategy		\$81	30	0%	10	0%	10	0%		\$24	\$81			\$81																		
1% gear efficiency improvement		\$297	62	2%			10	0%		\$184		\$0		\$297																		
Driveline																																
4x2 axle configuration			10	0%	10	0%	10	0%		\$0		\$0		\$0																		
5.29 drive axle ratio			10	0%	10	0%	10	0%		\$0		\$0		\$0																		
Baseline axle efficiency (90.5%)			70	0%						\$0		\$0		\$0																		
Axle efficiency with low friction lubricants (93%)		\$129	30	0%						\$39	\$0		\$0		\$0		\$0		\$0		\$0		\$O		\$0		\$C		\$			\$0
Advanced axle efficiency (97%)		\$509					10	0%		\$0	\$(\$0		\$0		\$0		\$0			\$509										
Tire rolling resistance	Steer	Drive	Steer	Drive	Steer	Drive	Steer	Drive	Steer	Drive	Steer	Drive	Steer	Drive																		
Level 1v	\$43	\$88							(\$43)	(\$88)	(\$43)	(\$88)	(\$43)	(\$88)																		
Level 2v	\$43	\$88							\$0	\$0	\$0	\$0	\$0	\$0																		
Level 3v	\$50	\$101		100%					\$0	\$101	\$O	\$O	\$0	\$0																		
Level 4v	\$57	\$113							\$0	\$0	\$0	\$0	\$0	\$0																		
Level 5v	\$57	\$113	100%		100%	100%			\$57	\$0	\$57	\$113	\$0	\$0																		
Level 6v	\$75	\$150							\$0	\$0	\$0	\$0	\$0	\$0																		
Level 7v	\$105	\$210					100%	100%	\$0	\$0	\$0	\$0	\$105	\$210																		
Aerodynamics																																
Skirt		\$431					100%			\$0	\$0		\$43																			
Nose cone		\$500					10	0%		\$0		\$0		\$500																		
Idle reduction																																
Neutral idle		\$127	60	0%	100%				\$76			\$127		\$0																		
Stop-start		\$844	3(0%				of mild orid)		\$253		\$0																				
Automatic engine shutdown		\$28	70	0%	10	0%		0%		\$19		\$28		\$28																		
Accessories																																
E-accessories (0.4 kW load reduction)		\$774	15	5%						\$116		\$0		\$0																		
Advanced e-accessories (0.8 kW load reduction)		\$1,549					10	0%		\$0		\$0		\$1,549																		
Other technologies																																
Tire pressure monitoring system		\$297	80	0%	10	0%	10	0%		\$237		\$297		\$297																		
Aluminum wheels (150 lbs)		\$652	50	0%						\$326		\$0		\$0																		
Advanced lightweighting (1,250 lbs)		\$2,191					10	0%		\$0		\$O		\$2,191																		
Bolt-on mild hybrid		\$7,672	6	%						\$460		\$0		\$0																		
Integrated mild hybrid with stop-start		\$8,876		%			10	0%		\$710		\$0		\$8,876																		
TOTAL										\$3,085		\$1,095		\$18,599																		



Figure A2. Cost per percent reduction in fuel consumption for heavy-duty tractor truck and medium-duty vocational vehicle engines.







12.0

10.0

8.0

6.0

4.0

2.0

0.0

High fuel cost;

3% discount rate

Payback time (years)

Fuel consumption reduction

\$0

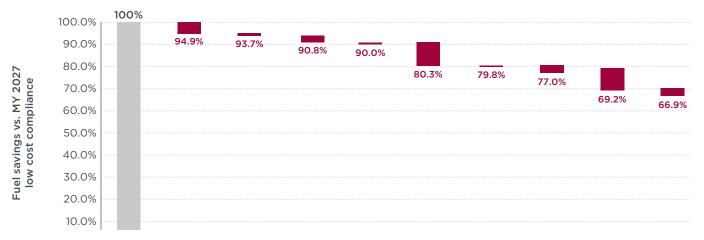


Figure A4. 2035 marginal costs, payback times, and fuel consumption reduction of Class 8 high-roof sleeper cab tractor-trailer technologies compared to the low-cost compliance vehicle in 2027.

Table A5. Class 8 high-roof sleeper cab tractor-trailers technologies and adoption rates projected under the Phase 2 standard compared to the EPA's projected best tractor-trailer in 2027. Technology potential not considered in the Phase 2 rulemaking is highlighted in yellow.

	Phase	e 2 standard i	n 2027	Projecte	d best-in-cl	ass in 2027		
Engine								
2027 compliant engine (49% peak BTE)		100%						
2027 compliant engine + WHR (50% peak BTE)					Х			
Transmission								
Automatic (with neutral idle)		30%						
Automated manual		50%			Х			
Dual clutch		10%						
1% gear efficiency improvement		70%						
Top gear direct drive		50%			Х			
Transmission-enabled								
2.31 final drive ratio		100%						
2.26 final drive ratio					Х			
Idle reduction								
Adjustable AESS		15%						
Adjustable AESS + diesel auxiliary power unit (APU)		40%						
Adjustable AESS + battery APU		15%						
Adjustable AESS + automatic stop-start		15%						
Adjustable AESS + fuel operated heater		15%						
Driveline								
6x2 axle configuration		30%		Х				
Baseline axle efficiency (93.5%)		20%						
Axle efficiency with low friction lubricants (95.4%)		80%						
Improved axle efficiency (96%)					Х			
Improved axle efficiency (96%) Tire rolling resistance	Steer	Drive	Trailer	Steer	X Drive	Trailer		
	Steer 5%	Drive 5%	Trailer	Steer		Trailer		
Tire rolling resistance			Trailer	Steer		Trailer		
Tire rolling resistance Baseline	5%	5%	Trailer 5%	Steer		Trailer		
Tire rolling resistance Baseline Level 1	5% 10%	5% 10%		Steer		Trailer		
Tire rolling resistance Baseline Level 1 Level 2	5% 10% 50%	5% 10% 50%		Steer		X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3	5% 10% 50%	5% 10% 50%	5%		Drive			
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4	5% 10% 50% 35%	5% 10% 50% 35% <i>5.8 kg/t</i>	5%	X	Drive X 4.5 kg/t	X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,)	5% 10% 50% 35% 5.6 kg/t	5% 10% 50% 35% <i>5.8 kg/t</i>	5% 95% 4.8 kg/t	× 4.3 kg/t	Drive X 4.5 kg/t	X 4.7 kg/t		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,,) Aerodynamics	5% 10% 50% 35% 5.6 kg/t Tractor	5% 10% 50% 35% <i>5.8 kg/t</i>	5% 95% 4.8 kg/t	× 4.3 kg/t	Drive X 4.5 kg/t	X 4.7 kg/t		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,) Aerodynamics Bin III	5% 10% 50% 35% 5.6 kg/t Tractor 20%	5% 10% 50% 35% <i>5.8 kg/t</i>	5% 95% 4.8 kg/t	× 4.3 kg/t	Drive X 4.5 kg/t	X 4.7 kg/t		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,,) Aerodynamics Bin III Bin IV	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30%	5% 10% 50% 35% <i>5.8 kg/t</i>	5% 95% 4.8 kg/t Trailer ^c	X 4.3 kg/t Tractor	Drive X 4.5 kg/t	X 4.7 kg/t Trailer		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,,) Aerodynamics Bin III Bin IV Bin V	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30%	5% 10% 50% 35% 5.8 kg/t	5% 95% <i>4.8 kg/t</i> Trailer ^c 30%	X 4.3 kg/t Tractor	Drive X 4.5 kg/t	X 4.7 kg/t Trailer		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,,) Aerodynamics Bin III Bin IV Bin V Bin VI	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C_r) Aerodynamics Bin III Bin V Bin VI Model input (C_dA) Intelligent controls Predictive cruise control	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C_n) Aerodynamics Bin III Bin V Bin V Bin VI Model input (C_nA) Intelligent controls Predictive cruise control Accessories	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C_r) Aerodynamics Bin III Bin V Bin VI Model input (C_dA) Intelligent controls Predictive cruise control	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C_n) Aerodynamics Bin III Bin V Bin V Bin VI Model input (C_nA) Intelligent controls Predictive cruise control Accessories	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t 	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistanceBaselineLevel 1Level 2Level 3Level 4Model input (C_v) AerodynamicsBin IIIBin VBin VBin VIModel input (C_cA) Intelligent controlsPredictive cruise controlAccessoriesHigh efficiency or electric A/C	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t 	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C_r) Aerodynamics Bin III Bin V Bin V Bin VI Model input $(C_{a}A)$ Intelligent controls Predictive cruise control Accessories High efficiency or electric A/C Improved accessories (1 kW load reduction)	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t - 40% 30%	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		
Tire rolling resistance Baseline Level 1 Level 2 Level 3 Level 4 Model input (C,,) Aerodynamics Bin III Bin V Bin V Bin VI Model input (C_dA) Intelligent controls Predictive cruise control Accessories High efficiency or electric A/C Improved accessories (1 kW load reduction) Advanced accessories (2 kW load reduction)	5% 10% 50% 35% 5.6 kg/t Tractor 20% 30% 50%	5% 10% 50% 35% 5.8 kg/t - 40% 30%	5% 95% 4.8 kg/t Trailer ^c 30% 70%	X 4.3 kg/t Tractor X	Drive X 4.5 kg/t	X 4.7 kg/t Trailer X		

Table A6. Tractor-trailer technology potential from this study compared to previous ICCT and EPA projections. Values correspond to Figure 7.

	Туре	Source	CO ₂ emissions (gCO2/ton-mi)	Fuel economy (mpg)	Payload (tons)
Tractor-trailer	Phase 2 tractor-trailer standards	This study, based on EPA rulemaking	57.7	9.3	19
	Best projected in 2027	EPA, 2015	54.5	9.8	19
	Technology potential in 2030ª	ICCT, 2015	46.8	11.6	18.7
	Two-year payback technology potential in 2035	This study	43.7	12.0	19.5
	Full technology potential in 2035	This study	37.9	13.8	19.4
Tractor only	Phase 2 tractor standard	EPA rulemaking	64.3	8.3	19
	Two-year payback technology potential in 2035	This study	49.7	10.6	19.3
	Full technology potential in 2035	This study	43.6	12.1	19

^a Modeled in Autonomie over a real-world highway cycle

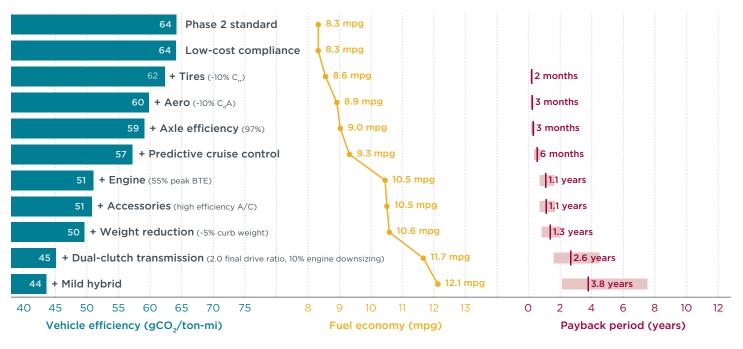
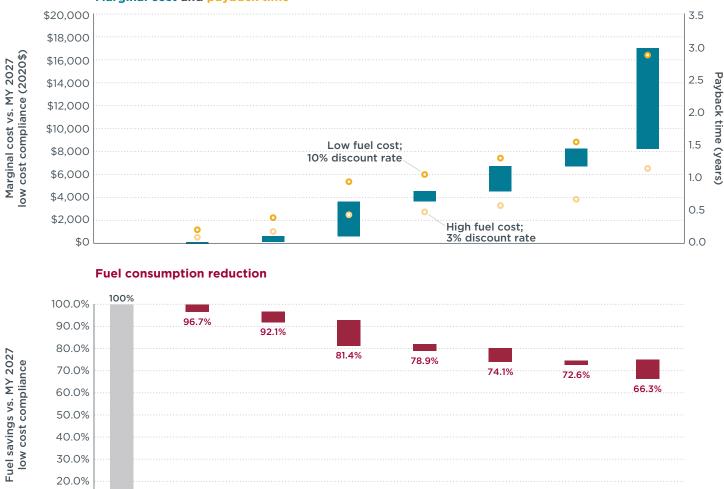


Figure A5. Vehicle efficiency, fuel economy, and payback period for incremental technology improvements from low-cost compliance with the Phase 2 standard for Class 8 high-roof sleeper cab tractors in model year 2027.



Engine

efficiency

Aerodynamics

Weight

reduction

Accessories

Transmission

Marginal cost and payback time

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Figure A6. 2035 marginal costs, payback times, and fuel consumption reduction of Class 6–7 multipurpose vocational vehicle technologies compared to the low-cost compliance vehicle in 2027.

Axle

efficiency

Tires

10.0%

38

MY 2027

low-cost

compliance